What Is Claimed Is:

- 1. A method for modifying a hexahedral volume mesh, comprising:
- generating a sheet of hexahedral elements from a hexahedral volume mesh, wherein said mesh includes a plurality of three-dimensional (3D) hexahedrons each having six quadrilateral faces
- and eight nodes, each node formed at three intersecting edges, and wherein said sheet includes a subset of the plurality of 3D hexahedrons;
- determining a group of hexahedrons within said sheet to refine;shrinking said group; and
- 8 inserting a new sheet of hexahedrons into the hexahedral volume mesh.
 - 2. The method of Claim 1, wherein the six quadrilateral faces for each 3D hexahedron include
- three sets of opposing faces, wherein generating a sheet includes:
 - selecting a first hexahedron, the selected hexahedron having a first set of opposing faces, the
- 4 first set including a first opposing face and a second opposing face;
 - determining a first neighboring hexahedron, the first neighboring hexahedron sharing the first
- 6 opposing face with the selected hexahedron;
 - selecting the first neighboring hexahedron, the first neighboring hexahedron having another face
- 8 opposite the shared first opposing face;
 - repeating steps b) and c) until a predetermined sheet edge threshold being satisfied;
- determining a second neighboring hexahedron, the second neighboring hexahedron sharing the second opposing face with the selected hexahedron;
- selecting the second neighboring hexahedron, the second neighboring hexahedron having another face opposite the shared second opposing face;
- repeating steps e) and f) until the sheet edge threshold being satisfied; grouping all selected hexahedrons into a first column of hexahedrons;
- selecting the first hexahedron, the selected hexahedron having a second set of opposing faces, the second set including a third opposing face and a fourth opposing face;

- determining a third neighboring hexahedron, the third neighboring hexahedron sharing the third opposing face with the selected hexahedron;
- selecting the third neighboring hexahedron;
 repeating steps a) through h) until a second column of hexahedrons is grouped;
- selecting the first hexahedron;
 - determining a fourth neighboring hexahedron, the fourth neighboring hexahedron sharing the
- 24 fourth opposing face with the selected hexahedron;
 - selecting the fourth neighboring hexahedron;
- repeating steps a) through h) until a third column of hexahedrons is grouped; repeating steps a) through p) until the sheet edge threshold being satisfied; and
- grouping all columns of hexahedrons into the sheet.
 - 3. The method of Claim 1, wherein generating a sheet includes:
- selecting a hexahedron, the selected hexahedron having three sets of opposing faces from the six quadrilateral faces, each set including a first opposing face and a second opposing face;
- determining a neighboring hexahedron to refine, the neighboring hexahedron sharing one face with the selected hexahedron;
- repeating step b) until all neighboring hexahedrons have been found; selecting the neighboring hexahedron to refine;
- 8 repeating steps a) through d) until all hexahedrons in the sheet have been found.
 - 4. The method of Claim 1, wherein determining a group of hexahedrons includes identifying said group using one of a point, line, and surface of the mesh.
- 5. The method of Claim 1, wherein determining a group of hexahedrons within said sheet to refine includes:

- selecting a hexahedron in the group to refine, the selected hexahedron having three sets of opposing faces from the six quadrilateral faces, each set comprising a first opposing face and a
- second opposing face;
- identifying the one set of opposing faces that are not shared by another hexahedron in the sheet, the set including a first unshared opposing face and a second unshared opposing face;
- 8 determining a distance between the first unshared opposing face and the second unshared opposing face;
- repeating steps a) through c) for each hexahedron in the group to refine; comparing the distance for each hexahedron in the group to refine;
- determining the hexahedron with a shortest distance;
 - calculating a ratio of the distance for each hexahedron in the sheet to refine to the shortest
- 14 distance;
 - comparing the ratio to a refinement threshold;
- grouping each hexahedron identified to refine into the group; and repeating steps g) through i) for each hexahedral in the group to refine.
 - 6. The method of Claim 1, wherein shrinking said group includes:

moving exterior nodes of the group from an original position into the volume of each hexahedron; and

maintaining a copy of each exterior node in the original position.

- 7. The method of Claim 1, wherein shrinking said group includes pillowing.
- 8. The method of Claim 1, wherein inserting a new sheet of hexahedrons into the hexahedral volume mesh includes:

separating each hexahedron in the group from the hexahedral volume mesh;

forming a void in the hexahedral volume mesh; and

inserting the new sheet of hexahedrons into the void.

- 9. A method for generating a hexahedral volume mesh by inserting a sheet of hexahedrons,
- 2 comprising:
 - generating an initial hexahedral volume mesh, wherein the mesh includes a plurality of three-
- dimensional (3D) hexahedrons, each 3D hexahedron having six quadrilateral faces and nodes, each node formed at three intersecting edges;
- 6 determining an area to refine in the initial mesh;
 - generating a sheet from said area, wherein the sheet includes a subset of the plurality of 3D
- 8 hexahedrons;
 - defining a group of hexahedrons within said sheet to refine;
- 10 shrinking said group; and
 - inserting a new sheet of hexahedrons into the hexahedral volume mesh.
 - 10) The method of Claim 9, wherein generating a sheet includes using a dual of the initial hexahedral mesh.
 - 11. The method of Claim 9, wherein determining an area to refine includes identifying said area using one of a point, line, and surface of the mesh.
 - 12. The method of Claim 9, wherein the initial hexahedral mesh is selected from the group consisting of an all-hexahedral swept mesh, multiple all-hexahedral swept meshes for a subdivided geometric entity, a quadrilateral mesh from a source surface to a target surface, and combinations thereof.
 - 13. The method of Claim 9, wherein the six quadrilateral faces for each 3D hexahedron include
- three sets of opposing faces, and wherein generating a sheet includes:
 - selecting a first hexahedron, the selected hexahedron having a first set of opposing faces, the
- 4 first set comprising a first opposing face and a second opposing face;
 - determining a first neighboring hexahedron, the first neighboring hexahedron sharing the first
- 6 opposing face with the selected hexahedron;
 - selecting the first neighboring hexahedron, the first neighboring hexahedron having another face
- 8 opposite the shared first opposing face;

- repeating steps b) and c) until a sheet edge threshold being satisfied;
- determining a second neighboring hexahedron, the second neighboring hexahedron sharing the second opposing face with the selected hexahedron;
- selecting the second neighboring hexahedron, the second neighboring hexahedron having another face opposite the shared second opposing face;
- repeating steps e) and f) until a sheet edge threshold being satisfied; grouping all selected hexahedrons into a first column of hexahedrons;
- selecting the first hexahedron, the selected hexahedron having a second set of opposing faces, the second set comprising a third opposing face and a fourth opposing face;
- determining a third neighboring hexahedron, the third neighboring hexahedron sharing the third opposing face with the selected hexahedron;
- selecting the third neighboring hexahedron;
 repeating steps a) through h) until a second column of hexahedrons is grouped;
- selecting the first hexahedron;
 - determining a fourth neighboring hexahedron, the fourth neighboring hexahedron sharing the
- 24 fourth opposing face with the selected hexahedron;
 - selecting the fourth neighboring hexahedron to refine;
- repeating steps a) through h) until a third column of hexahedrons is grouped; repeating steps a) through p) until the sheet edge criterion is met; and
- 28 grouping all columns of hexahedrons into the sheet.

- 14. The method of Claim 9, wherein generating a sheet includes:
- selecting a hexahedron, the selected hexahedron having three sets of opposing faces from the six quadrilateral faces, each set including a first opposing face and a second opposing face;
- determining a neighboring hexahedron, the neighboring hexahedron sharing one face with the selected hexahedron;
- repeating step b) until all neighboring hexahedrons have been found; selecting the neighboring hexahedron;
- repeating steps a) through d) until all hexahedrons in the sheet have been found.
 - 15. The method of Claim 9, wherein determining a group of hexahedrons within said sheet to refine includes:
- selecting a hexahedron in the group to refine, the selected hexahedron having three sets of opposing faces from the six quadrilateral faces, each set comprising a first opposing face and a second opposing face;
- identifying the one set of opposing faces that are not shared by another hexahedron in the sheet, the set comprising a first unshared opposing face and a second unshared opposing face;
- determining a distance between the first unshared opposing face and the second unshared opposing face;
- repeating steps a) through c) for each hexahedron in the group to refine; comparing the distance for each hexahedron in the group to refine;
- 20 determining a hexahedron with a shortest distance;
 - calculating a ratio of the distance for each hexahedron in the group to refine to the shortest
- 22 distance;

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- comparing the ratio to a refinement threshold;
- grouping each hexahedron identified to refine into the group; and repeating steps g) through i) for each hexahedral in the group to refine.

16. The method of Claim 9, wherein shrinking said group includes:

moving exterior nodes of the group from an original position into the volume of each hexahedron; and

maintaining a copy of each exterior node in the original position.

- 17. The method of Claim 9, wherein shrinking said group includes pillowing.
- 18. The method of Claim 9, wherein inserting a new sheet of hexahedrons into the hexahedral volume mesh includes:

separating each hexahedron in the group from the hexahedral volume mesh;

forming a void in the hexahedral volume mesh; and

inserting the new sheet of hexahedrons into the void.

- 19. A sheet insertor for modifying a hexahedral mesh, comprising:
- 2 a controller for performing the steps of:
 - generating a sheet of hexahedrons from a hexahedral mesh, wherein the mesh includes a
- 4 plurality of 3D hexahedrons, and wherein said sheet including a subset of the plurality of 3D hexahedrons;
- 6 determining a group of hexahedrons within said sheet to refine;
 - separating each hexahedron in the group from the hexahedral volume mesh to form a void; and
- 8 inserting a new sheet of hexahedrons into the void.
 - 20. The sheet insertor of Claim 19, wherein controller further performing the steps of:
- selecting a hexahedron, including three sets of opposing faces, wherein each set includes a first opposing face and a second opposing face;
- selecting a neighboring hexahedron, including three sets of opposing faces, the neighboring hexahedron sharing one face with the selected hexahedron; and

- selecting a plurality of other neighboring hexahedrons, each neighboring hexahedron 6 comprising three sets of opposing faces, each neighboring hexahedron sharing a face with another hexahedron.
- 21. The sheet insertor of Claim 19, wherein determining a group of hexahedrons within said

determining a plurality of hexahedrons in the group to refine;

determining a hexahedron with the shortest distance;

sheet to refine includes:

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determining a ratio of the distance for each hexahedron in the group to the shortest distance and comparing the ratio with a refinement threshold.

- 22. The sheet insertor of Claim 19, wherein determining a group of hexahedrons includes identifying said group using one a point, line, and surface of the mesh.
- 23. A method for modifying a hexahedral volume mesh, comprising:

inserting a volume into a hexahedral volume mesh forming an intersection, wherein the mesh includes a plurality of 3D hexahedrons, each 3D hexahedron having eight nodes, each node formed at three intersecting edges;

moving nodes in the hexahedral mesh to surface of intersection with the volume;

inserting a layer of elements on each side of the volume; and removing the volume.

24. A method for generating a hexahedral volume mesh by mesh cutting, comprising:

generating an initial hexahedral mesh including a plurality of 3D hexahedrons, each hexahedron having a plurality of nodes;

inserting a volume into the initial hexahedral mesh forming an intersection;

moving nodes in the hexahedral mesh to surface of intersection with the volume;

inserting a layer of elements on each side of the volume; and

removing the volume.

25. A mesh cutter for cutting a hexahedral volume mesh, comprising:

a controller for performing the steps of:

generating an initial hexahedral mesh including a plurality of 3D hexahedrons, each hexahedron having a plurality of nodes;

inserting a volume into the initial hexahedral mesh forming an intersecting having a surface; and inserting a layer of elements on each side of the volume.

- 26. A method for modifying a volume mesh, comprising:
- 2 connecting a plurality of rows of elements of a volume mesh using connecting lines, where said connecting lines, together with associated planes, form a plurality of three-dimensional regions,
- said plurality of three-dimensional regions forming a sheet of volume mesh elements from said mesh;
- determining a plurality of hexahedral elements within said sheet to refine using a predetermined threshold for each one of said plurality;
- forming a void between said plurality of hexahedral elements and said mesh;
 inserting a new sheet of hexahedral elements into said void to produce a modified form of said
 volume mesh.
- 27. A machine-readable medium having stored thereon a plurality of executable instructions, the
 plurality of instructions comprising instructions to:
 - connect a plurality of rows of elements of a volume mesh using connecting lines, where said
- 4 connecting lines, together with associated planes, form a plurality of three-dimensional regions, said plurality of three-dimensional regions forming a sheet of volume mesh elements from said
- 6 mesh;
 - determine a plurality of hexahedral elements within said sheet to refine using a predetermined
- 8 threshold for each one of said plurality;
 - form a void between said plurality of hexahedral elements and said mesh;

- insert a new sheet of hexahedral elements into said void to produce a modified form of said volume mesh.
 - 28. A method for modifying a volume mesh, comprising:
- 2 connecting a plurality of rows of elements of a volume mesh using connecting lines, where said connecting lines, together with associated planes, form a plurality of three-dimensional regions,
- said plurality of three-dimensional regions forming a sheet of volume mesh elements, each mesh element including a plurality of surfaces;
- determining at least one node linking a plurality of surfaces in said sheet using a predetermined algorithm;
- disconnecting a plurality of said connecting lines, together with a plurality of said associated planes, at said at least one node and removing a portion of said plurality of connecting lines,
- together with a portion of said plurality of associated planes, in a predetermined direction away from said point to form a void in said mesh;
- inserting a new sheet of hexahedral elements into said void to produce a modified form of said volume mesh.
- 29. A machine-readable medium having stored thereon a plurality of executable instructions, the plurality of instructions comprising instructions to:
 - connect a plurality of rows of elements of a volume mesh using connecting lines, where said
- 4 connecting lines, together with associated planes, form a plurality of three-dimensional regions, said plurality of three-dimensional regions forming a sheet of volume mesh elements, each
- 6 mesh element including a plurality of surfaces;
 - determine at least one node linking a plurality of surfaces in said sheet using a predetermined algorithm;
- disconnect a portion of said connecting lines, together with a portion of said associated planes, at said at least one node and removing said portion in a predetermined direction away from said point to form a void in said mesh;

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- insert a new sheet of hexahedral elements into said void to produce a modified form of said volume mesh.
 - 30. A method for modifying a volume mesh, comprising:
- connecting a plurality of rows of elements of a volume mesh using connecting lines, where said connecting lines, together with associated planes, form a plurality of three-dimensional regions,
- said plurality of three-dimensional regions forming a sheet of volume mesh elements from said mesh:
- 6 inserting a volume including elements within said volume into said mesh at the sheet forming an intersection having a surface between said volume and the mesh;
- associating nodes at said surface including adding a plurality of layers to existing mesh elements at the surface;
- removing said volume including the elements within said volume to produce a modified form of said volume mesh.
- 31. A machine-readable medium having stored thereon a plurality of executable instructions, the plurality of instructions comprising instructions to:
 - connect a plurality of rows of elements of a volume mesh using connecting lines, where said
- 4 connecting lines, together with associated planes, form a plurality of three-dimensional regions, said plurality of three-dimensional regions forming a sheet of volume mesh elements from said
- 6 mesh:
 - insert a volume including elements within said volume into said mesh at the sheet forming an
- 8 intersection having a surface between said volume and the mesh;
- associate nodes at said surface including adding a plurality of layers to existing mesh elements at the surface;
- remove said volume including the elements within said volume to produce a modified form of said volume mesh.